Matrix Operations (in Chemistry)

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Motivation

Eigenvectors

- Normal modes, vibrational spectra
- Principal Components Analysis (PCA)

Eigenvalues

- Energy levels of an Hamiltonian
- Molecular graph comparison

Matrix inverse

- Solving systems of linear equations
- Machine learning methods

Matrix multiplication

- Symmetry operations

 \mathbf{v}_i

 λ_i

 \mathbf{A}^{-1}

Eigenvectors and eigenvalues

Eigenvectors

- Multiplication with A leaves direction unchanged
- Invariants of a (symmetry) transformation
- Must be non-zero

Eigenvalues

- Linked to eigenvectors
- Set of all is called spectrum

$$\mathbf{A}\mathbf{v}_i = \lambda_i \mathbf{v}_i$$
$$(\mathbf{A} - \lambda_i \mathbf{I})\mathbf{v}_i = 0$$

Normal modes

Hessian

- Local curvature of the potential energy
- If in local minimum: vibrational modes

Normal modes

- Mass-weighted Hessian F_{ij} = $H_{ij}(M_iM_j)^{-1/2}$
- Eigenvalues: Frequencies
- Eigenvectors: Modes

$$\mathbf{H} = \begin{bmatrix} \frac{\partial^2 E}{\partial x_1^2} & \frac{\partial^2 E}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 E}{\partial x_1 \partial x_n} \\ \frac{\partial^2 E}{\partial x_2 \partial x_1} & \frac{\partial^2 E}{\partial x_2^2} & \cdots & \frac{\partial^2 E}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 E}{\partial x_n \partial x_1} & \frac{\partial^2 E}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 E}{\partial x_n^2} \end{bmatrix},$$

```
from pyscf import gto
import numpy as np
from pyscf.data import nist
# Build molecule
mol = gto.M(atom=[['0', 0., 0., 0.106817],
                 ['H', 0., -0.785198 , -0.427268],
                 ['H', 0., 0.785198, -0.427268]],
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mf = mol.RHF().run()
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hessian = mf.Hessian().kernel()
# Change the array Layout
hessian = hessian.transpose(0, 2, 1, 3).reshape(mol.natm * 3, mol.natm * 3)
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atom_masses = np.repeat(atom_masses, 3)
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force constants, modes = np.linalg.eigh(weighted hessian)
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frequencies = np.sqrt(np.abs(force_constants))
to wavenumbers = (nist.HARTREE2J / (nist.ATOMIC MASS * nist.BOHR SI**2))**.5
to_wavenumbers *= 1/(2 * np.pi) / nist.LIGHT_SPEED_SI * 1e-2
to wavenumbers * np.sort(frequencies)[-3:]
array([1736.71755055, 3988.23212533, 4145.21010618])
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Imports

- PySCF: Quantum chemistry calculations
- Numpy: Mathematical operations

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Define a molecule: water

- Coordinates (need to be a minimum!)
- Basis set: measure of accuracy

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Do the actual calculation

- Restricted Hartree-Fock as a method
- For large molecules: expensive

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Calculate the analytical Hessian

- For large molecules: even more expensive

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Change the memory layout

- PySCF returns the Hessian as fourdimensional array (atom1, atom2, dimension1, dimension2)
- We need it as square symmetric matrix

np.transpose()

- Transposes a matrix = changes axes order
- By default: reverse axes
- Here: Sort into (atom1, dimension1, atom2, dimension2)

np.reshape()

- Keeps data, looks at it differently
- Here: Makes matrix square

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Build list of atomic masses

PySCF has built-in data sets, no copying required

np.repeat()

- Repeats each element
- Once for each dimension

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Build mass-weighting matrix

- Note that np.sqrt() is operating elementwise
- matrix * matrix is elementwise (np.matmul() would be matrix multiplication)

np.outer()

- Outer product
- Pairwise multiplication:
 M_{ii} = m_im_i

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Get eigenvalues

From weighted Hessian(!)

np.eigh()

- For symmetric matrices
- Otherwise: *np.eig()*

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```

Get frequencies from force constants

- Harmonic approximation
- Negative and small entries:
 3 translational and 3 rotational degrees
 of freedom

np.abs()

- Absolute value
- Here: shortcut (better: remove translational and rotational degrees first)

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Convert to wavenumbers

- PySCF has predefined constants

PySCF can do it

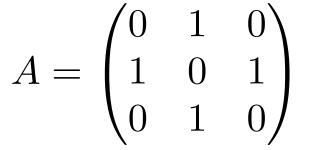
Eigenvalue spectrum

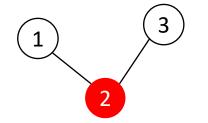
Definition

- Unordered set of eigenvalues
- Invariant under permutations

Adjacency matrices

- 1 if there is a bond between atom *i* and *j*
- 0 otherwise
- Graph property, many useful algorithms









Eigenvalues

- $-\pm 2^{1/2}$, 0
- np.linalg.eigh()[0]

Solving systems of linear equations

Core idea

- Collect terms in matrix
- Invert matrix
- Matrix vector product

np.linalg.inv()

Inverts the matrix

np.dot()

Matrix vector product

Overdetermined case

- np.linalg.pinv()
- Pseudoinverse
- Alternative for least-squares fit

$$\mathbf{A}\mathbf{x} = \mathbf{b} \Rightarrow \mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$$

Determinant

Application

- System unsolvable, i.e. A not invertible: det(A) = 0
- np.linalg.det()

$$\mathbf{A}\mathbf{x} = \mathbf{b} \Rightarrow \mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$$

Pitfalls

Numerics

- Matrix inversion unstable
- Machine epsilon introduces inaccuracies
- Hint: do not simplify algorithms you implement

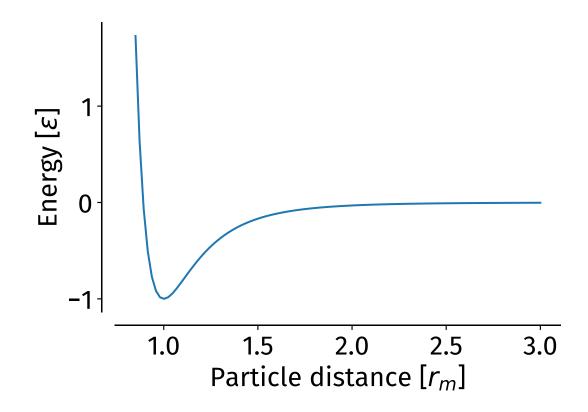
Resources

- Matrices become large quickly
 - 1GB: *N*=12k
 - 10GB: *N*=36k
- Matrix operations scale worse
 - Matrix multiplication scales as $N^{-2.8}$

Matrix exponentiation

Numerics

- Matrix multiplication scales as $N^{-2.8}$
- Group matrix operations $A^4 = (A^2)^2$
- Works for scalars as well
 - Reason why Lennard-Jones potential is commonly used



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Unstable matrix inversion

Simple case

- Hilbert matrix
- $H_{ij} = 1/(i+j-1)$

$$H = \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & \frac{1}{6} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & \frac{1}{6} & \frac{1}{7} \\ \frac{1}{4} & \frac{1}{5} & \frac{1}{6} & \frac{1}{7} & \frac{1}{8} \\ \frac{1}{5} & \frac{1}{6} & \frac{1}{7} & \frac{1}{8} & \frac{1}{9} \end{bmatrix}$$

(6.143234069592521e-15, 351.1986284929532)

```
def hilbert_matrix(N):
    idx = np.arange(0, N)
   hilbert = 1 / (np.repeat(idx, N) + np.tile(idx, N) + 1)
    return hilbert.reshape(N, N)
def check_inverse(matrix):
    inverse = np.linalg.inv(matrix)
    product = np.matmul(inverse, matrix)
    deviations = product - np.identity(matrix.shape[0])
    return np.max(np.abs(deviations))
check_inverse(hilbert_matrix(3)), check_inverse(hilbert_matrix(15))
```

```
Largest absolute error
                                                 11
                                         9
                          Size of Hilbert matrix
```

10⁻⁴ -

Symmetry operations

Matrices are common tools

- Entries encode geometrical change
- pymatgen implements these

y = Ax

Identity

$$\mathbf{I} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \qquad \mathbf{x} = \mathbf{I}\mathbf{x}$$

Reflection in the xy-plane

$$\mathbf{R}_{xy} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \qquad \mathbf{x}' = \mathbf{R}_{xy}\mathbf{x}$$

Symmetry operations

Inversion

$$\mathbf{T} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \qquad \mathbf{T}^2 = \mathbf{I}$$

Rotation around x

$$\mathbf{R}_{x} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \alpha & -\sin \alpha \\ 0 & \sin \alpha & \cos \alpha \end{pmatrix} \qquad C_{n} : \alpha = \frac{2\pi}{n}$$

General tip

Try to make any problem you face either

- A matrix
- A graph
- An optimization problem

Advantages

- Huge literature on either topic
- Efficient algorithms
- Reliable libraries with interfaces to Python

Libraries in Python

- Matrix: numpy / scipy
- Graph: NetworkX (easy but slow, good visualisation)
- Graph: igraph (fast, but quite technical interface)
- Optimisation: *scipy* (easy interface)
- Optimisation: DEAP (global optimization, quite technical interface)

Summary

Operations

- Eigenvalues / Eigenvectors
- Matrix multiplications
- Matrix inversions
- Solving systems of linear equations

Caveats

- Numerical stability
- Memory requirements

Python

- pymatgen for symmetry operations





